Deformation Models for Image and Video Generation

Stéphane Lathuilière

LTCI, Télécom Paris, Institut polytechnique de Paris, France



Multimedia and Human Understanding Group (MHUG), University of Trento, Italy



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Why do we need to generate images and videos?

Artistic / Editing / marketing purposes

Photo editing



Augmented reality ^a

 Many other applications: video games, increasing some intrinsic image properties...

^aimage from *zugara* company

Machine Learning Tasks

• Generate annotated data: Head pose [1]



- Learning from few samples
- Domain adaptation



S.Lathuilère, R.Juge, P.Mesejo, R.Munoz-Salinas, R.Horaud, Deep Mixture of Linear Inverse Regressions Applied to Head-Pose estimation, CVPR 2017

From Noise to Image



^[4] P.Isola, J.-Y.Zhu, T.Zhou, A.A.Efros, Image-to-Image Translation with Conditional Adversarial Networks, CVPR, 2017

From Noise to Image



Image-to-Image translation [4]



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Pose-based Human Image Generation [5]



^[5] L. Ma, X. Jia, Q. Sun, B. Schiele, T. Tuytelaars, and L. Van Gool, Pose-guided person image generation, NIPS, 2017



^[5] L. Ma, X. Jia, Q. Sun, B. Schiele, T. Tuytelaars, and L. Van Gool, Pose-guided person image generation, NIPS, 2017

Pose-based Human Image Generation



Pose-based Human Image Generation



We need a deformation model!





^[6] A. Siarohin, E. Sangineto, S. Lathuilière, N. Sebe, Deformable GANs for Pose-based Human Image Generation, CVPR, 2018



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The body parts are combined:

$$d(F) = max_{h=1,...,10}F'_h,$$
(1)

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• \mathcal{L}_1 and \mathcal{L}_2 produce blurred images.



We propose a *nearest-neighbour* loss \mathcal{L}_{NN}

- Compute in a feature space g(x).
- $g(\cdot)$: externally trained network.

$$\mathcal{L}_{1}^{g}(\hat{x}, x_{b}) = \sum_{\mathbf{p} \in g(\hat{x})} ||g(\hat{x})(p) - g(x_{b})(p)||_{1},$$
(2)

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$$\mathcal{L}_{NN}(\hat{x}, x_b) = \sum_{\mathbf{p} \in g(\hat{x})} \min_{\mathbf{q} \in \mathcal{N}(\mathbf{p})} ||g(\hat{x})(\mathbf{p}) - g(x_b)(\mathbf{q})||_1,$$
(3)

 ${\ensuremath{\, \bullet }}$ where $\mathcal{N}(\mathbf{p})$ is a $n \times n$ local neighbourhood of point \mathbf{p}

Pose-based Human Image Generation: ablation



Figure: Qualitative results on the Market-1501 dataset.

Pose-based Human Image Generation: ablation



Figure: Qualitative results on the DeepFashion dataset.

Table: Comparison with the state of the art on the DeepFashion dataset.

Model	SSIM	IS
Ma et al. [7]	0.762	3.090
Ma et al. [8]	0.614	3.228
Esser et al. [9]	0.786	3.087
<i>Ours</i>	0.756	3.439

^[7] L. Ma, X. Jia, Q. Sun, B. Schiele, T. Tuytelaars, and L. Van Gool, Pose-guided person image generation, NIPS, 2017

^[8] L. Ma, Q. Sun, S. Georgoulis, L. Van Gool, B. Schiele, and M. Fritz, Disentangled person image generation, CVPR, 2018

^[9] P. Esser, E. Sutter, and B. Ommer, A variational u-net for conditional appearance and shape generation, CVPR, 2018

Pose-based Human Image Generation: Re-ID

Query	1 2 3 Gallery	4 5
IDE	E + Euclidean [10] <i>Rank 1</i>	Discr. Embedding [11] <i>Rank 1</i>
No augmentation	73.9	78.3

Table: Data augmentation for Re-ID on the Market-1501 (*Rank 1* in %).

[12] A. Siarohin, S. Lathuilière, E. Sangineto, N. Sebe, Appearance and Pose-Conditioned Human Image Generation using Deformable GANs, TPAMI, 2019

^[7] L.Ma, X.Jia, Q.Sun, B.Schiele, T.Tuytelaars, and L.Van Gool, Pose-guided person image generation, NIPS, 2017

^[9] P. Esser, E. Sutter, and B. Ommer, A variational u-net for conditional appearance and shape generation, CVPR, 2018

^[10] L.Zheng, Y.Yang, and A.G.Hauptmann, Person re-identification: Past, present and future, arXiv, 2016

^[11] Z. Zheng, L. Zheng, and Y. Yang, A discriminatively learned CNN embedding for person reidentification, TOMCCAP, 2018

Pose-based Human Image Generation: Re-ID

Query 1 2 3 4 5 Gallery Callery				
	IDE + Euclidean [10] <i>Rank 1</i>	Discr. Embedding [11] <i>Rank 1</i>		
No augmentation	73.9	78.3		
<i>Ours (Full)</i> [12]	78.9	81.4		

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^[7] L.Ma, X.Jia, Q.Sun, B.Schiele, T.Tuytelaars, and L.Van Gool, Pose-guided person image generation, NIPS, 2017

^[9] P. Esser, E. Sutter, and B. Ommer, A variational u-net for conditional appearance and shape generation, CVPR, 2018

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Pose-based Human Image Generation: Re-ID



	IDE + Euclidean [10] <i>Rank 1</i>	Discr. Embedding [11] <i>Rank 1</i>
No augmentation	73.9	78.3
Ours (Full) [12]	78.9	81.4
Ours (Baseline)	68.1	70.6
Ma et al. [7]	66.9	73.9
Esser et al. [9]	58.1	63.1

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[12] A. Siarohin, S. Lathuilière, E. Sangineto, N. Sebe, Appearance and Pose-Conditioned Human Image Generation using Deformable GANs, TPAMI, 2019

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^[11] Z. Zheng, L. Zheng, and Y. Yang, A discriminatively learned CNN embedding for person reidentification, TOMCCAP, 2018



- Multiple input images
- How to select the relevant information in each image depending on:
 - pose difference
 - potential occlusions
 - image quality

^[13] S. Lathuilière, A. Siarohin, E. Sangineto, and N. Sebe, Attention-based Fusion for Multi-source Human Image Generation, WACV 2020



^[14] O.Ronneberger, P.Fischer, and T.Brox, U-Net: Convolutional Networks for Biomedical Image Segmentation



Skip connections

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We propose [13]:

 $)\odot oldsymbol{\xi}_{r}^{i},$ Att(features skip

connection

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We propose [13]: $F_{r} = \sum_{i=1}^{M} Att(\underbrace{\psi_{r}}_{\text{features}}, \underbrace{\xi_{r}^{i}}_{\text{skip}}) \odot \xi_{r}^{i}, \quad (4)$

^[13] S. Lathuilière, A. Siarohin, E. Sangineto, and N. Sebe, Attention-based Fusion for Multi-source Human Image Generation, WACV 2020



Figure: A qualitative evaluation on the Market-1501 dataset.

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Pose-guided generation for video generation?



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Naive solution: appearance transfer



Problems:

• It requires a detector



^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019

Problems:

• It requires a detector



• Does not work when the shapes of the object are different



^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019

Problems:

• It requires a detector



• Does not work when the shapes of the object are different



We propose: Self-supervised Motion Transfer [15].

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019

Self-supervised Motion Transfer [15]



Self-supervised training.

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019



Self-supervised training.

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019



Image animation at test time.

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019



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Again, we have an alignment problem.

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Image animation: Results

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		Tai-Chi		Ne	emo (Fac	ce)	Bair
	\mathcal{L}_1	AKD	AED	\mathcal{L}_1	AKD	AED	\mathcal{L}_1
X2Face [16]	0.068	4.50	0.27	0.022	0.47	0.140	0.069
Ours [15]	0.050	2.53	0.21	0.017	0.37	0.072	0.025

 Table:
 Video reconstruction comparisons.
 We employ AKD: Average Keypoint

 Distance and AED:
 Average Euclidean Distance

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019

^[16] X2Face: A network for controlling face generation by using images, audio, and pose codes. O.Wiles, A.S.Koepke, A. Zisserman, ECCV 2018

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 Table:
 Video reconstruction comparisons.
 We employ AKD: Average Keypoint

 Distance and AED:
 Average Euclidean Distance

Tai-Chi	Nemo	Bair
85.0%	79.2%	90.8%

Table: User study results on image animation. Proportion of times our approach is preferred over X2face [16].

^[15] A. Siarohin, S. Lathuilière, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer , CVPR 2019

^[16] X2Face: A network for controlling face generation by using images, audio, and pose codes. O.Wiles, A.S.Koepke, A. Zisserman, ECCV 2018



$$\mathcal{T}_{\mathbf{X}\leftarrow\mathbf{R}}(p) = \mathcal{T}_{\mathbf{X}\leftarrow\mathbf{R}}(p_k) + o(\|p - p_k\|),$$
(5)

^[17] A. Siarohin, S. Lathuilière, S. Tulyakov, E. Ricci, N. Sebe, First Order Motion Model for Image Animation , NeurIPS 2019



$$\mathcal{T}_{\mathbf{X}\leftarrow\mathbf{R}}(p) = \mathcal{T}_{\mathbf{X}\leftarrow\mathbf{R}}(p_k) + \left(\frac{d}{dp}\mathcal{T}_{\mathbf{X}\leftarrow\mathbf{R}}(p)\Big|_{p=p_k}\right)(p-p_k) + o(\|p-p_k\|), \quad (5)$$

^[17] A. Siarohin, S. Lathuilière, S. Tulyakov, E. Ricci, N. Sebe, First Order Motion Model for Image Animation , NeurIPS 2019



Future works:

- Improve activity recognition methods
- Condition motion on other inputs
- Compression for video call (e.g. Skype)

Thank You! Thanks to Aliaksandr, Sergey, Enver, Elisa and Nicu!

- A. Siarohin, E. Sangineto, S. Lathuilière, N. Sebe, Deformable GANs for Pose-based Human Image Generation, CVPR 2018
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- S. Lathuilière, A. Siarohin, E. Sangineto, and N. Sebe, Attention-based Fusion for Multi-source Human Image Generation, WACV 2020
- A. Siarohin, **S. Lathuilière**, S. Tulyakov , E. Ricci, N. Sebe, Animating Arbitrary Objects via Deep Motion Transfer, CVPR 2019
- A. Siarohin, S. Lathuilière, S. Tulyakov, E. Ricci, N. Sebe, First Order Motion Model for Image Animation, NeurIPS 2019